



**SYNTEC LATHE
CONTROLLER
MODEL 11TB, 200TB-5,
210TB-H, 210TB-H5, 220TB &
220TB-5**

| Controller type | Multi – Axis Group Mill-Turn | | | | | |
|------------------------|------------------------------|-------------------------------|--------------------|------------|--------------------|-----------|
| | 11TB | 200TB – 5 | 210TB – H | 210TB – H5 | 220TB | 220TB – 5 |
| Axis no. | 8 | 12(16) | 12(16) | | 12(16) | |
| DA | 2 | 1 | 2 | | – | |
| Max I/O | 128/128 | 96/96 | 96/96 | | 128/128 | |
| Display | 10.4” | 8”/10.4” | 8”/10.4”/rear haft | | 10.4”/15” | |
| Servo | Pulse | M2 | M2/M3/ECAT/RTEX | | M3/ECAT/RTEX | |
| VGA | – | O | O* | | – | |
| Connection | Ethernet RS485 | Ethernet RS232 RS422 RS485 | Ethernet RS485 SRI | | Ethernet RS485 SRI | |
| Multi-Program No. | 2 | 4 | 4 | 4 | 4 | 4 |
| Memory | 512MB | 256MB | 4GB | 4GB | 4GB | 4GB |
| Inclined Plane process | | Δ | – | Δ | – | Δ |
| HPCC | | Δ | – | Δ | – | Δ |

*VGA is only provided for the rear half

○ Standard

– Not Support

Δ Optional

| Category | Items | Multi Axis Group Mill Turn | | | | | |
|-----------------------|--|----------------------------|---------|---------|----------|--------|---------|
| | | 11TB | 200TB-5 | 210TB-H | 210TB-H5 | 220TB | 220TB-5 |
| Product specification | Max. Axes group in system | 2 | 4 | 4 | | 4 | |
| | Max. PLC axes group | 1 | 3 | 3 | | 3 | |
| | Standard controlled axes (standard) | 8 | 12 | 12 | 12 | 12 | 12 |
| | Max. controlled axes (option) | 8 | 16 | 16 | 16 | 16 | 16 |
| | Max. Number of spindles | 6 | 6 | 6 | | 6 | |
| | Max. Axes in synchronous control (single axes group) | 4 | 5 | 4 | 5 | 4 | 5 |
| | Min. Control unit-mm | 0,0001 | 0,0001 | 0,0001 | | 0,0001 | |
| | Max. Number of work coordinates system | 100 | 100 | 100 | | 100 | |
| | Max. Groups of tool compensation | 96 | 96 | 96 | | 96 | |
| | Number of multi-channel function groups | 4 | 4 | 4 | | 4 | |
| | Number of pre-read segments | 1000 | 2000 | 2000 | | 2000 | |
| | Segment process time | 1000 | 4000 | 1000 | 4000 | 1000 | 4000 |

| | | | | | |
|------------------------|--------------------|---------|--------|---------------------|---------|
| Hardware specification | Storage DISKA (MB) | 512 | 256 | 4096 | 4096 |
| | I/O standard | 64/64 | 32/32 | 32/32 | 32/32 |
| | I/O optional | 128/128 | 96/96 | 96/96 | 128/128 |
| | DA | 2 | 2 | 2 | 2 |
| | Display (Inch) | 10,4 | 8/10.4 | 8/10.4/rear half*** | 10.4/15 |
| | CF card | — | — | — | — |
| | USB | 2 | 1 | 2 | 2 |
| | RJ-45 | 1 | 2 | 1 | 2 |
| | VGA output | — | 1 | 1*** | — |
| | PS/2 | — | 1 | — | — |
| | RS-232 | — | 1 | — | — |
| | RS-422 | — | 1 | — | — |
| | RS-485 | 1 | — | 1 | 1 |
| | USB | — | 2 | — | 2 |
| | SRI | — | — | 1 | 1 |

| | | | | | |
|---------------|-----------------------------|---|---|---|---|
| Servo control | General purpose (A/B phase) | 0 | — | — | — |
| | General purpose (CW/CCW) | 0 | — | — | — |
| | Mechatrolink II | — | 0 | 0 | 0 |
| | Mechatrolink III | — | — | 0 | 0 |
| | EtherCAT | — | — | 0 | 0 |
| | RTEX | — | — | 0 | 0 |
| Compensation | Back gap compensation | 0 | 0 | 0 | 0 |
| | Pitch error compensation | 0 | 0 | 0 | 0 |
| | Spike compensation | 0 | 0 | 0 | 0 |
| | Temp. Rise compensation | 0 | 0 | 0 | 0 |
| | 2D compensation | 0 | 0 | 0 | 0 |
| Operation | Handwheel simulation | 0 | 0 | 0 | 0 |
| | Program empty run | 0 | 0 | 0 | 0 |
| | Selective stop | 0 | 0 | 0 | 0 |
| | Segment execution | 0 | 0 | 0 | 0 |
| | Virtual handwheel | 0 | 0 | 0 | 0 |
| | Pause point start | 0 | 0 | 0 | 0 |
| | Tool interrupt point start | 0 | 0 | 0 | 0 |
| | Tool retract | — | — | — | — |
| | Offset setting | 0 | 0 | 0 | 0 |
| | Handwheel offset function | — | — | — | — |

| | | | | | |
|---------------------------|---|---|---|---|---|
| Program input | Selective jump | 0 | 0 | 0 | 0 |
| | B-STOP/ program end | 0 | 0 | 0 | 0 |
| | Absolute zero coordinates system (G92/G92.1) | 0 | 0 | 0 | 0 |
| | Interrupt MACRO (M96/M97) | 0 | 0 | 0 | 0 |
| | M 198 call subroutine | 0 | 0 | 0 | 0 |
| | G-code extension | 0 | 0 | 0 | 0 |
| High speed high precision | Constant Jerk control | 0 | 0 | 0 | 0 |
| | Cross-segment S-curve acceleration/ deceleration | 0 | 0 | 0 | 0 |
| | Auto deceleration at corner | 0 | 0 | 0 | 0 |
| | Corner radius speed limit | 0 | 0 | 0 | 0 |
| | Multiple high speed high precision parameter set | — | — | — | — |
| | User quick parameter | — | — | — | — |
| | SPA function | — | — | — | — |
| | Virtual circle radius function | 0 | 0 | 0 | 0 |
| | High speed high precision control mode I (G05.1Q1) | — | — | — | — |
| | High speed high precision control mode ii (G05P10000) | — | — | — | — |
| Tool management | NURBS interpolation function | — | — | — | — |
| | Auto tool align screen | — | — | — | — |
| | Auto work measurement | 0 | 0 | 0 | 0 |
| | Tool lifespan management | 0 | 0 | 0 | 0 |

| | | | | | |
|--------------------|--|---|---|---|---|
| Auxiliary function | Mechanical lock (R-Bit) | 0 | 0 | 0 | 0 |
| | Software travel limit | 0 | 0 | 0 | 0 |
| | Spindle speed detection | 0 | 0 | 0 | 0 |
| | Axial coupling function | 0 | 0 | 0 | 0 |
| | Axial dynamic coupling function | 0 | 0 | 0 | 0 |
| | Feedback coupling function | 0 | 0 | 0 | 0 |
| | Threading quick tool retract | 0 | 0 | 0 | 0 |
| | Virtual axis function | 0 | 0 | 0 | 0 |
| | Axle exchange function | 0 | 0 | 0 | 0 |
| | Axial torque control | — | 0 | 0 | 0 |
| | Serial adjustment function (CNC axis) | — | 0 | 0 | 0 |
| | Driver data display (CNC axis) | — | 0 | 0 | 0 |
| | Spindle adaptation function (CNC axis) | — | 0 | 0 | 0 |
| | Serial PLC axis | — | 0 | 0 | 0 |
| | High speed spindle positioning (SYNTEC spindle required) | — | 0 | 0 | 0 |
| | ROT element | — | 0 | 0 | 0 |
| | Dipole foreground/ background configuration | 0 | 0 | 0 | 0 |
| | Data backup and recover | 0 | 0 | 0 | 0 |
| | Start-up screen customization | 0 | 0 | 0 | 0 |
| | My favorite (Only support ARM 8-key system) | 0 | — | 0 | 0 |
| | Project protection function | 0 | 0 | 0 | 0 |
| | Access management | 0 | 0 | 0 | 0 |
| | Remote AP monitoring | 0 | 0 | 0 | 0 |

| | | | | | |
|------------------------|--|---|---|---|---|
| Programming | Background edit | O | O | O | O |
| | Edit protection | O | O | O | O |
| | Real time syntax check of processing program | O | O | O | O |
| PLC | PLC diagnosis function (FORCE I-point) | O | O | O | O |
| Data transfer function | NETWORK | O | O | O | O |
| | FTP | O | O | O | O |
| | RS-485 | O | O | O | O |
| | DNC(Network) | O | O | O | O |
| | DNC(USB) | O | O | O | O |
| Data display | Operation history display | O | O | O | O |
| | Graphic simulation | O | O | O | O |
| | Partial graphic simulation | O | O | O | O |
| | Dynamic multi-language switch- over | O | O | O | O |

| | | | | | |
|--------|---|---|---|---|---|
| G-code | Oval cutting (clockwise) (G02.1) | 0 | 0 | 0 | 0 |
| | Parabolic cutting (clockwise) (G02.2) | 0 | 0 | 0 | 0 |
| | Cylinder interpolation (G07.1) | 0 | 0 | 0 | 0 |
| | Start-up polar coordinates (G12.1) | 0 | 0 | 0 | 0 |
| | OD/ID turning cycle (G20) | 0 | 0 | 0 | 0 |
| | Threading cycle (G21) | 0 | 0 | 0 | 0 |
| | Intermediate threading feed cycle (G21.2) | 0 | 0 | 0 | 0 |
| | End face turning cycle (G24) | 0 | 0 | 0 | 0 |
| | Jump function (G31) | 0 | 0 | 0 | 0 |
| | Treading (G33) | 0 | 0 | 0 | 0 |
| | Variable pitch threading (G34) | 0 | 0 | 0 | 0 |
| | Polygon turning (G51.2) | 0 | 0 | 0 | 0 |
| | Work coordinates system setting (G54~G59.9) | 0 | 0 | 0 | 0 |
| | Mirror function (lathe) (G68) | 0 | 0 | 0 | 0 |
| | Complex turning cycle (G72~G78) | 0 | 0 | 0 | 0 |
| | Fixing cycle for drilling (G80, G83~G89) | 0 | 0 | 0 | 0 |
| | Absolute zero coordinates system preset (G92.1) | 0 | 0 | 0 | 0 |
| | Inverse time feed (G93) | — | — | — | — |
| | Constant surface cutting speed (G96) | 0 | 0 | 0 | 0 |
| | Spindle synchronization function (G114.1) | 0 | 0 | 0 | 0 |
| | Spindle load function (G114.3) | 0 | 0 | 0 | 0 |

Option

| | | | | |
|--|---|---|---|---|
| Option-4 Enable Plugin Function | O | O | O | O |
| Option-11 High Precision Contour Control (HPCC) | | | | |
| Option-12 Rotation Tool Center Point (RTCP) | | Δ | Δ | Δ |
| Option-13 Feature Coordinate System | | Δ | Δ | Δ |
| Option-14 Parameter learning function | | | | |
| Option-15 Tapping Learning | | | | |
| Option-16 Syntec Vision | | | | |
| Option-17 Commercial Vision Software | | | | |
| Option-18 CAD/CAM | | | | |
| Option-19 3D Arc Interpolation | | | | |
| Option-20 Pick and Place (All in one) | | Δ | Δ | Δ |
| Option-21 Four Axis Robot | | | | |
| Option-22 Five Axis Robot | | | | |
| Option-23 Six Axis Robot | | | | |
| Option-24 Gantry Robot | Δ | | | |
| Option-25 Advanced Look-Ahead | | | | |
| Option-26 Smooth Tool Center Point(STCP) | | | | |
| Option-27 Multiple mechanisms for five-axis | | | | |
| Option-28 The 2nd coordinate supports feature coordinate system | | | | |
| Option-29 Four-axis Rotation Tool Center Point Control (4AXRTCP) | | | | |
| Option-31 High Speed Chamfering Contour Control | | | | |
| Option-32 ROT Servo Turret | | Δ | Δ | Δ |
| Option-34 Wood Software | | | | |
| Option-35 3D Laser Scanning | | | | |
| Option-36 Wood Built-In CAM Function | | | | |

* Only sell in Mainland China

** Only sell in Taiwan

*** VGA is only provided in the rear half

O Standard function

Δ Optional function

– Not available function